2021 Rocky Mountain Regional Programming Contest

Solution Sketches

RMRC 2021 Solution Sketches

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• For each option, the answer is simply $\frac{100}{p}$ where *p* is the percentage bet on that option.

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- To lose an election, you can afford to win as many as $\lfloor \frac{N}{2} \rfloor$ regions—assume you win all votes in these regions.
- For the remaining regions, you may win up to ⌊^p/₂⌋ votes and still lose.
- Greedy algorithm: win the regions with the $\lfloor \frac{N}{2} \rfloor$ highest population.

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- If there is a gap of length g between consecutive people, we can fit ⌊(g − 1)/2⌋ more people in that gap.
- Sum this value over all gaps.
- Don't forget about the gap between the last and first person in the input.

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H - RSA Mistake (17/108)

- Factor both numbers using trial division up to the square root. Takes $O(\sqrt{n})$ time to factor *n*. Fast enough for this problem as both numbers are $\leq 10^{12}$.
- If either number is divisible by a prime more than once or if the two numbers share a prime in common: no credit.
- Otherwise, if either number is not a prime: partial credit.
- Otherwise, full credit.

- Scan left-to-right through both arrays at once.
- Maintain a frequency counter as you scan: *freq*[x] is the difference between the number of copies of item x scanned so far from the first array minus the number of copies of x scanned so far from the second array.
- Also maintain a value ∆ indicating how many keys x are such that *freq*[x] ≠ 0.
- If Δ ever becomes 0, place a divider.

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- Simulate the algorithm and remember a "timestamp" so that each time *s* or *e* is incremented, the timestamp is incremented.
- In other words, the timestamp counts the number of windows encountered so far.
- During the simulation, record the timestamp at which w_i enters the window (i.e. when e = i)
- When the window leaves w_i (i.e. when s = i + 1), compute the difference in timestamps.

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L - Ticket Completed? (11/54)

- Create a graph *G* with the *n* cities as vertices and any claimed rail segments as edges.
- Find the connected components *C_i* within the graph (e.g. using BFS or DFS).
- For each connected component of k vertices, there are ^k₂ destination tickets that can be satisfied.
- The probability that a random pair of cities will be connected is the total number of satisfied destination tickets (across all connected components) divided by the total number of unique destination tickets:

$$\frac{\sum_{C_i} \binom{|C_i|}{2}}{\binom{n}{2}}$$

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- For each candidate word in the dictionary:
 - Check whether each guess' feedback is consistent given the candidate word.
 - If the feedback is consistent for all guesses, output the word.

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G - Loot Chest (6/10)

- Recall: the expected number of times you need to flip a coin until you see heads if the coin has probability p of being heads is 1/p.
- So the expected number of times you need to open a prize pack is 1/(G/100).
- Just need to compute the expected number of games until you open a prize pack.
- **Dynamic Programming**: If *e*[*P*] is the expected number of games until you open a prize pack given that your current probability of getting a pack is *P* is then:
 - e[100] = 1/(1 L/100) (keep playing until you win)
 - $e[P] = 1 + \frac{1}{100} \cdot e[P + \Delta_L] + (1 \frac{1}{100}) \cdot (1 \frac{P}{100}) \cdot e[P + \Delta_W]$ for $0 \le P \le 99$. That is, you play a game. If you lose, *P* goes up by Δ_L and if you win but don't get a prize pack, then *P* goes up by Δ_W . Make sure to cap the new *P* value at 100 (eg. use min(100, $P + \Delta$) whenever *P* goes up by Δ).

J - Snowball Fight (3/8)

- Single-step simulation is too slow.
- Look for patterns. For example, if all three are distinct, say A < B < C, then we can simulate Δ := min B A, C B steps in a single calculation: subtract Δ from B and 2Δ from A. After this, two values are the same.
- If two values are the same, they will follow the same pattern until they are within, say, 4 of each other (or some get close to 0). Example: A = B = 80, C = 100. Every 2 rounds, A and B will go down by 1 and C by 4 until C is within 1 of A, B.
- If they are within 4 of each other, just do single step simulation until they are within 1 of each other.
- If all 3 have the same health: Rubble!

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J - Snowball Fight (3/8)

- If they are within 1 of each other, every 3 rounds each will go down by 3.
- If there are only 2 left, easy to tell.
- If two of them have small health (say ≤ 4), then you should just simulate to avoid corner cases in the big-step simulation rules.
- Carefully combining these ideas leads to a solution with running time *O*(1). Just be extra careful to get the details right!

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- The flowers (nodes) and vines (edges) can be represented as a graph. In fact it is a tree.
- We can solve this recursively on the tree.
- For each node *r*, define *f*(*r*, *s*, *b*) as the largest total pollination power possible for the subtree rooted at *r* and the total size of the selected families is *s*.
- *b* is a boolean flag indicating whether the root *r* must be skipped (e.g. if parent node has been chosen).

- At each node, combining the answers from subtrees is essentially a knapsack problem.
- This can be solved in $O(NS^2)$ time.

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K - Team Change (1/2)

- Consider a graph G with vertices == players and edges == conflicts.
- Label each vertex as **must change**, **must not change**, and **doesn't matter**.
- After deleting some players, it is possible to form teams if and only if each component of the resulting graph does not have both a **must change** and a **must not change** player.
- Cast as a min-cut problem where you cut vertices. Create 2 new nodes C, N representing **change** and **not change**. Connect C to each vertex that must change, N to each vertex that must not change, and find a min-size N T vertex cut.
- Input was small enough that even Ford-Fulkerson is fast enough.

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M - Trade Routes (1/5)

- The greedy algorithm is correct: process the routes *i* in order of value (greatest to least). If adding *i* to the current set of chosen routes is feasible, do it.
- But that is too slow.
- Idea: push the solution "upward". For each vertex *j*, compute the optimal solution for nodes lying in the subtree under *j* (i.e. as if *j* was Rome) and store in an ordered set R_j
- To compute R_j for j, take the b_j most valuable items in $\{j\} \cup_{j' \text{ child of } j} R_{j'}$ (or all of them if there are less than b_j).
- This is still too slow.

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M - Trade Routes (1/5)

- The final trick is when merging two sets, say R_j and $R_{j'}$, to always add the items from the smaller of the two to the larger and regard the larger as the new merged set.
- Each item is "moved" to a new set O(log n) times since the size of the resulting set is at least twice as large as the original set. Each movement takes O(log n) time if you use an ordered set (or a binary heap). So O(n ⋅ log² n) time in total.
- Can do in $O(n \cdot \log n)$ times using heaps that support O(1) insertion, but they aren't in standard libraries. The above idea is fast enough.

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- For each query, there are four boundary segments for that pixel.
- Repeatedly clip given polygon against the four segments.
- Exact arithmetic needs to be used.